



## Sensibility analysis of the FO CRS traveltimes approximation

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This paper was prepared for presentation at the 8<sup>th</sup> International Congress of The Brazilian Geophysical Society held in Rio de Janeiro, Brazil, 14-18 September 2003.

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### Abstract

The 2-D finite-offset (FO) Common-Reflection-Surface (CRS) stack simulates a specified 2-D finite-offset (FO) section (e.g., a common-offset (CO) section), and is able to handle P-P, S-S reflections and P-S or S-P converted reflections, respectively. Also large-offset reflections can be utilized in this process. This approach depends on five stacking parameters: two angles and three wavefront curvatures, which are determined from the seismic data by means of a coherence analysis. These parameters are related to kinematic wavefield attributes useful in several problems. The five kinematic wavefield attributes can be considered for further use in inversion, e.g., macro-model inversion and Amplitude-versus-Offset (AVO) analysis. In this paper we investigate the sensibility of the FO CRS stacking operator with respect to the kinematic data-derived attributes. By analysing the first derivative of the FO CRS traveltimes with respect to each one of the searched-for parameters, we describe the behavior of the FO CRS stacking surface.

### Introduction

In recent years, stacking methods as the POLYSTACK (e.g. de Bazelaire (1988)), Multifocusing (e.g. Gelchinsky et al. (1999a,b); Landa et al. (1999)) and the Common-Reflection-Surface (CRS) (e.g. Mann et al. (1999); Jäger et al. (2001); Trappe et al. (2001)) have gained a new importance in seismic process. These techniques have been used to stack P-P reflection events in 2-D pre-stack multi-coverage data and to simulate zero-offset sections. To handle also converted reflections in the frame of the CRS stack, the zero-offset (ZO) CRS stack has been generalized to stack pre-stack data into a selected FO section (Zhang et al., 2001).

The FO CRS stacking operator is constituted by five parameters, which have to be searched-for in a coherence-based, data-driven way (Zhang et al., 2001). The FO CRS stack has demonstrated the applicability not only to P-P or S-S reflections, but also to seismic multi-coverage data containing converted reflections, where the emergence angle information provided by the FO CRS stack can be used to reliably separate P-P from P-S reflections. The inline

geometrical spreading factor can, for instance, be computed from the attributes, which is of help for AVO analysis (Bergler et al., 2001a). The FO CRS stack parameters may be used to determine in a subsequent traveltimes inversion the P-wave velocity and/or S-wave velocity of a layered earth model (Bergler et al., 2001b).

As part of the inverse problem, we describe the behavior of the FO CRS stack surface, by analysing the first derivative of the FO traveltimes approximation with respect to each of the searched-for parameters.

### Basic Theory

The FO CRS stacking operator (Zhang et al., 2001) for converted and non-converted reflections in dependence of midpoint ( $x_m$ ) and half-offset ( $h$ ) coordinates of the paraxial ray (Figure 1) is given by

$$t^2 = \left[ t_0 + \left( \frac{\sin \beta_G}{v_G} + \frac{\sin \beta_S}{v_S} \right) (x_m - x_0) \right. \\ \left. + \left( \frac{\sin \beta_G}{v_G} - \frac{\sin \beta_S}{v_S} \right) (h - h_0) \right]^2 \\ + 2t_0 \left[ \left( K_3 \frac{\cos^2 \beta_G}{v_G} + K_2 \frac{\cos^2 \beta_S}{v_S} \right) (h - h_0) \right. \\ \left. + \frac{1}{2} \left( K_3 \frac{\cos^2 \beta_G}{v_G} - K_2 \frac{\cos^2 \beta_S}{v_S} \right) (h - h_0)^2 \right. \\ \left. + \left( (4K_1 - 3K_3) \frac{\cos^2 \beta_G}{v_G} - K_2 \frac{\cos^2 \beta_S}{v_S} \right) \frac{(x_m - x_0)^2}{2} \right], \quad (1)$$

where  $t_0$  is the reflection traveltimes along the central ray,  $x_0$  and  $h_0$  being the midpoint and half-offset coordinates of the central ray.  $x_m$  and  $h$  are the midpoint and half-offset coordinates of the paraxial ray.  $\beta_S$  and  $\beta_G$  are the incidence angle and the emergence angle of the central ray at the source  $S$  and the receiver  $G$ , respectively (Figure 1).  $v_S$  and  $v_G$  are the wave velocities at the source and receiver, respectively.  $K_1$  is the resulting wavefront curvature at the receiver  $G$  in the seismic line of a wave emanated from a point source  $S$  and traveled along the central ray in the real common-shot (CS) experiment (Figure 2).  $K_2$  and  $K_3$  are the wavefront curvatures of a fictitious wave at source  $S$  and receiver  $G$  of the central ray, respectively, where each paraxial ray that starts at the coordinate  $x_0 - h$  on the seismic line emerges after reflection at the coordinate  $x_0 + h$  in the hypothetical common-midpoint (CMP) experiment (see Figure 2). Formula (1) represents a second-order traveltimes approximation of paraxial rays in the vicinity of the

central ray.

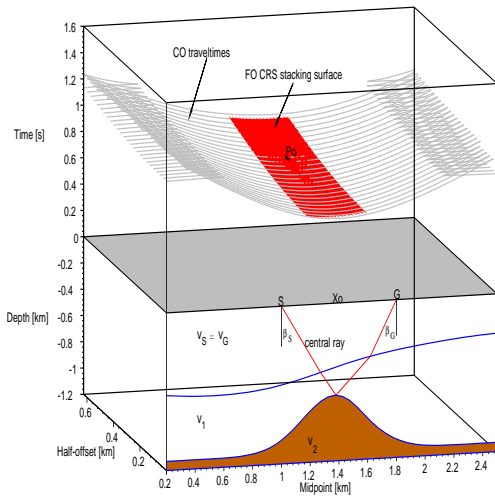


Figure 1: Upper part: Example of P-P kinematic reflection response from the dome-like reflector represented by the CO traveltimes (grey). The reflection response is approximated by the FO CRS stacking surface. Lower part: a 2D medium consisting of two homogeneous layers about a half-space, bounded by curved interfaces.

**Sensibility Analysis**

The most important step to obtain a simulated finite-offset section by the FO CRS stack traveltimes is to perform an accurate and efficient parameter search of these five parameters. We investigate how sensitive is the operator on the variations of the searched-for parameters. This is done by analysing the first derivative of the moveout formula (1) with respect to each one of the parameters.

These derivatives, are shown in the Figures 3 to 8. We remind that in this analysis we considered for a fixed point  $P_0(x_0 = 1.4km, h_0 = 0.4km, t_0 = 0.7364s.)$  (Figure 1). The traveltimes derivative with respect to  $\beta_S$  presents higher positive values at smaller and larger offsets and midpoints far from central point  $P_0$ . This does not occur with the derivate with respect to  $\beta_G$ , which presents smaller negative and positive values. The traveltimes derivative with respect to  $K_1$  presents higher positive values at smaller and larger offsets and midpoint far from central point. The same does not occur with the derivative with respect to  $K_2$ , where the values are negatives. Finally, the derivative with respect to  $K_3$  presents negative values at smaller and larger offsets and midpoint near and far from the central point. This last derivate also presents smaller positive values at larger offsets.

**Conclusions**

By using traveltimes derivatives of the FO CRS traveltimes approximation, we have analyzed the sensibility of the operator with respect to each of the searched-for parameter.

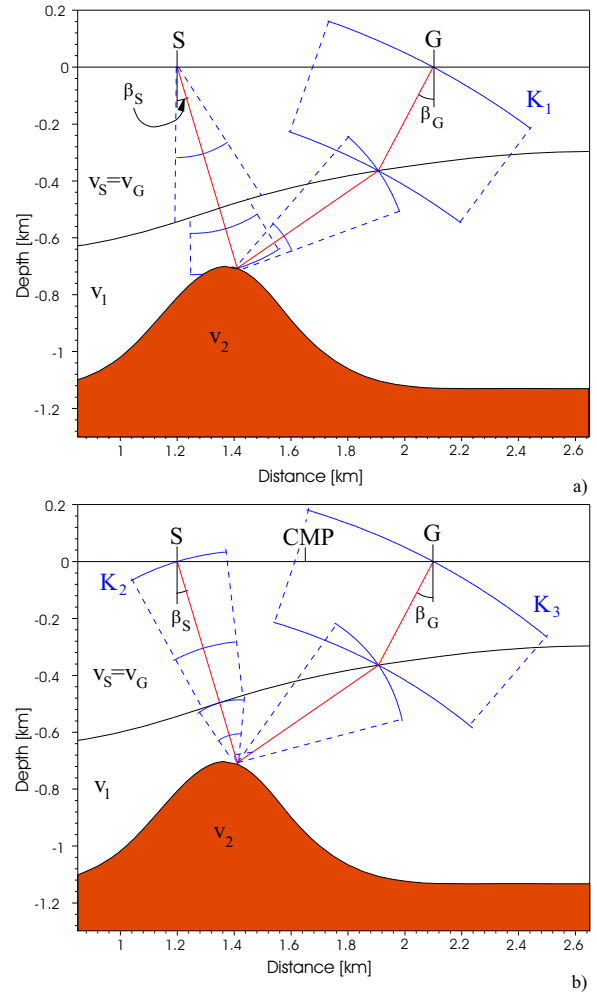


Figure 2: Wavefront curvatures ( $K_1$ ,  $K_2$  and  $K_3$ ) associated to two experiments: a) real CS experiment, and b) hypothetical CMP experiment in an isotropic model with constant-velocity layers (modified from Bergler et al. (2001b)).

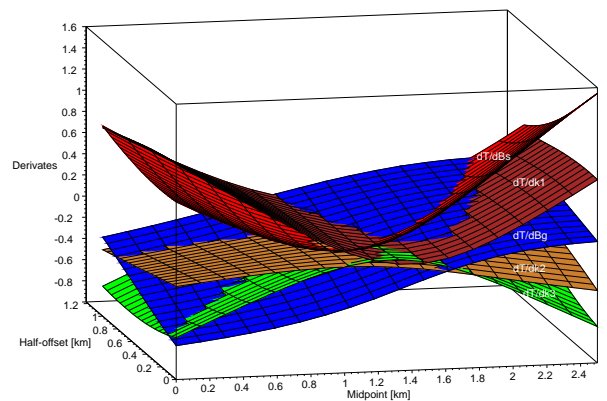


Figure 3: FO CRS traveltimes derivatives for the five stacking parameters.

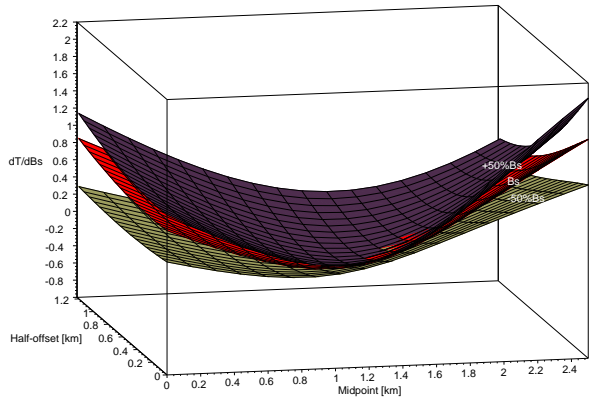


Figure 4: FO CRS traveltimes derivatives by using variations ( $-50, +50$  percentages) and true values in the angle  $\beta_S$ , between half-offset: 0-1.2 km in increments of 0.025 km.

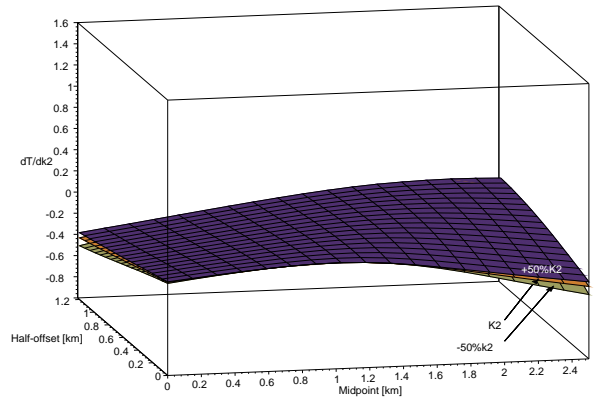


Figure 7: The FO CRS stacking surface by using variations ( $-50, +50$  percentages) and true values in the wavefront curvatures  $K_2$ , between half-offset: 0-1.2 km in increments of 0.025 km.

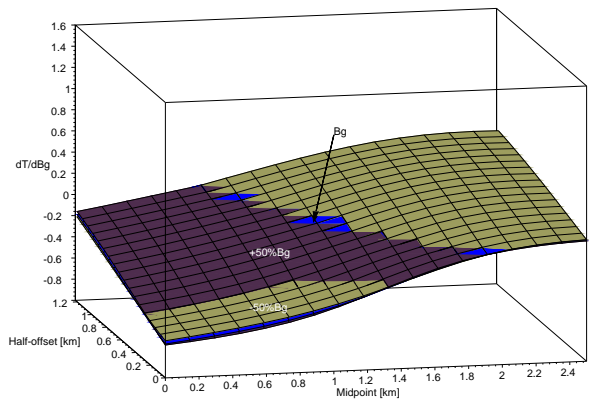


Figure 5: FO CRS traveltimes derivatives by using variations ( $-50, +50$  percentages) and true values in the angle  $\beta_G$ , between half-offset: 0-1.2 km in increments of 0.025 km.

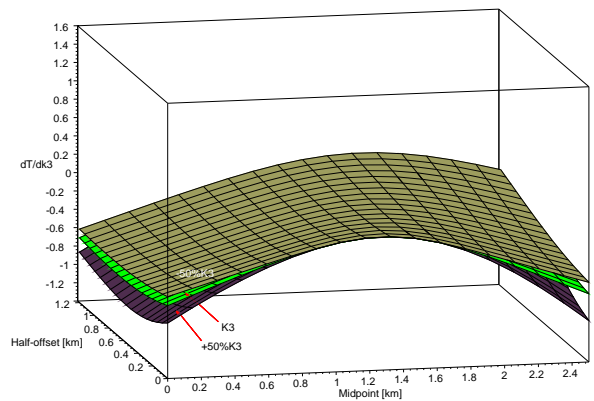


Figure 8: The FO CRS stacking surface by using variations ( $-50, +50$  percentages) and true values in the wavefront curvatures  $K_3$ , between half-offset: 0-1.2 km in increments of 0.025 km.

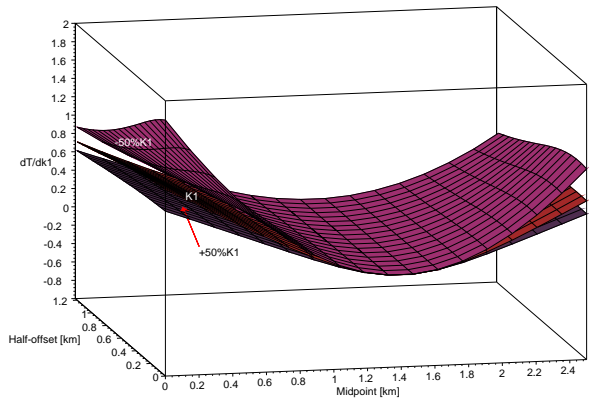


Figure 6: The FO CRS stacking surface by using variations ( $-50, +50$  percentages) and true values in the wavefront curvature  $K_1$ , between half-offset: 0-1.2 km in increments of 0.025 km.

For the central point studied the traveltine function is very sensitive to the  $\beta_S$  and  $K_1$ . This is an indicator that both parameters ( $\beta_S, K_1$ ) can be very well determined by the inverse problem solution. In the case of the parameters  $\beta_G, K_2$  and  $K_3$ , this operator is less sensitive. In this case these parameters are poorly determined during the search procedure, that suggests to use some constraint to better determining the parameters  $\beta_G, K_2$  and  $K_3$ .

### Acknowledgments

We thank the support of the WIT Consortium (Germany).

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